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	Technical Concept	Template Number:	Page 1 of 15

Document Title:	Accelerator and Beam Modes
Description:	Technical Concept for definition and integration of Accelerator Modes and Beam Modes in the accelerator control system
Division/Organization:	CSCO, PBSP
Field of application:	Project FAIR@GSI, existing GSI accelerator facility
Version	V 0.2

Abstract

This technical concept proposes two fundamental modes: the '*accelerator mode*' covering rule sets and operational sequence outside of beam operation and that are defined per accelerator or beam-line section (e.g. shutdown, setup, physics run, etc.); and the '*beam mode*' covering rule sets during beam operation and that are defined per accelerator or beam-line section and Beam-Production-Chain (e.g. no beam, pilot beam, stable beam, etc.).

The purpose of these modes is to communicate the intended accelerator operation, and to condition the various control sub-system responses (e.g. archiving, interlock and fast-beam-abort systems, management of critical settings, etc.). The accelerator control system will distribute this information to the accelerator devices, experiments and wider FAIR community.

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- Purpose:

- A) Communication of intended accelerator operation to experiments, FAIR and wider community

- what to expect and when

- B) Conditioning of control sub-system responses

- e.g. logging, interlocks, management of critical settings (RBAC), machine sequencer, access system, ...

→ associated rules of what is allowed, when, where etc. some examples:

- limit parameter changes during data taking – aka. 'Stable Beams'
- no beam data being logged during 'shut-down' period
- no high-intensity beam injected into an 'empty' machine
- block certain operation during un-safe mode of operation, e.g.
 - moving in beam screens during production runs
 - settings change that could affect efficiency/safety of machine operation (e.g. slow-extraction)
 - uncontrolled remote tests on an operational devices during beam operation

Mode:

- **deliberate user-driven state** used to precondition the control system behaviour and responses independent of the actual accelerator or beam state → 'reference' or 'desired target' of operation (long-term)
 - formal agreement between accelerator operations and experimental users w.r.t. what to expect
- Tracked by operator (initially) and semi-automated sequencer to follow normal operational sequence
 - Example 1: 'Shut-Down' → 'Cool-Down' → 'Machine Check-Out'
 - Example 2: ... → 'no beam' → 'pilot beam' → 'intensity ramp-up' → 'adjust' → 'stable beams/production for physics' → ...
 - need to limit number of mutually exclusive and concise modes ↔ overhead of settings generation and their checks
- no real-time requirements

Actual State:

- **measured current state** of the accelerator/beam (short-term)
 - perviates accelerator & beam mode definition & equally used as a ad-hoc/post condition
 - Examples: Beam-Presence-Flag (BPF), Setup-Beam-Flag (SBF), Injection & Extraction Permit (MP interlock states)
- real-time requirements
- **Examples:**
 - 'No Beam' beam mode declares intend (as an agreement) that there will be no beam in the machine
 - 'Beam Presence Flag' is measured actual state whether there is (/was) beam in the machine or not
 - N.B. obviously a 'NO BEAM' beam mode & 'BPF=true' should lead to an interlock
- **Shouldn't mix 'modes' with 'actual states' to prevent circular dependencies, priority/causality inversions**

- Main modes:

- 1) Accelerator (Machine) Modes

- covering rule sets outside of beam operation
 - defined per accelerator/transfer-line segment

- 2) Beam Modes

- covering rule sets during beam operation
 - defined per accelerator/transfer-line segment and beam-production-chain

- Main Actual States:

- Beam Presence Flag (BPF)

- indicates that settings have been validated with Setup- (Pilot-) or Physics-Beam
 - prevents high-intensity injections into an 'empty' machine with new untested magnetic settings or modified machine conditions

- Setup Beam Flag (SBF)

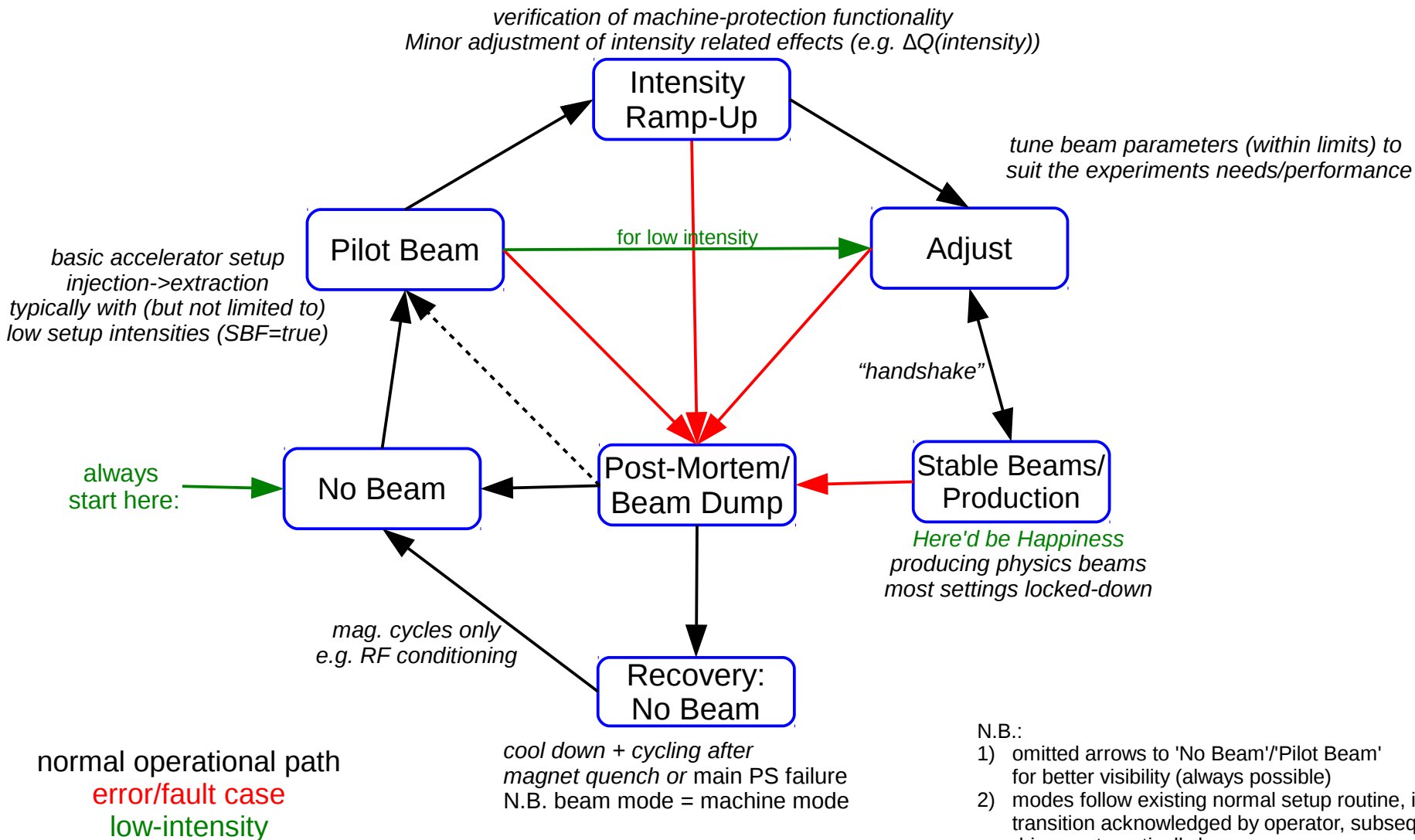
- Indicates beam used to setup beam production chain (typ. low-intensity)
 - SBF provides flexibility of masking interlocks during setup periods
 - rationale: interlocks targeted for high-intensity operation may impact setup and availability with low-intensities
 - defined per accelerator or transfer-line segment (where necessary)

		Accelerator Mode										
		Shut-down	Cool-down	Bake-Out	Warm-Up	Beam Operation						Machine Development
						Machine-Checkout	Access	Machine Test	Beam Setup	Physics		
Beam Mode	No Beam	X	X	X	X	X	X	X	X	X	X	X
	Pilot Beam								X	X	X	
	Intensity Ramp-Up								X	X	X	
	Adjust								X	X	X	
	Stable Beams										X	
	Post-Mortem								X	X	X	
	Recovery								X	X	X	

N.B. defined per accelerator/transfer line segment

N.B. defined per accelerator/transfer line segment & beam production chain

concatenation of <accelerator mode>:<beam mode>
e.g. 'Shut-down:No Beam', 'Physics:Pilot Beam'



Follows annual life-cycle of accelerator facility

- **Operation without Beam:**

- SHUTDOWN
 - could imply possibility of open/controlled access or no powering
- COOLDOWN (SIS100, SFRS)
 - typ. 2-3 weeks, limited/no access
 - need to distinguish between a 'warm' and cold' shutdown?
- BAKE-OUT (SIS18, HEBT, ...) – similar to cool-down
- WARM-UP (SIS100, SFRS)
- RECOVERY (SIS100, SFRS)
 - after quench, partial vacuum loss, typ. few hours - day
 - includes e.g. periodic magnet CYCLING to stabilise hysteresis
- MACHINE-CHECKOUT
 - operations tests without beam in view of beam operation
 - (e.g. power converter calibration, magnet patrol, etc.)
 - done once after a long shutdown, typ. few weeks before beam operation
- ACCESS (during beam operation periods)
 - controlled access for specific tasks only (signature by MCs & OP)

operation without beam
(part of shut-down coordination)

- **Operation with Beam:**

- BEAM SETUP or MACHINE SETUP
 - focus on initial/re-commissioning, machine setup after long shut-down + OP training
- PHYSICS
- MACHINE DEVELOPMENT
 - focus on accelerator/beam physics aspects
- MACHINE TEST (during beam operation periods)
 - controls, RF, new front-end, ... tests w/o beam + OP training
 - Ad-hoc during beam operation but not 'Physics' nor 'MD'

describe main aim
of machine operation
+
info & Accounting
type modes

- Follows life-cycle of beam setup and production – also not new, de-facto how
 - **NO BEAM**
 - prevent/stop beam being injected by design (\leftrightarrow mode)
 - **PILOT BEAM** – alternate: Beam Setup?
 - Establishing main machine parameters: injection steering, RF capture, ramp, orbit, Q/Q', optics checks, extraction
 - typically done with low setup-intensities
 - **INTENSITY RAMP-UP** – should we differentiate stages? e.g.: INT. RAMP-UP #1, INT. RAMP-UP #2, ... ?
 - beam parameter tuning and checks related to increasing intensities (e.g. slow extraction, space-charge, etc.)
 - check of interlocks & machine protection functionalities (limited user group only \leftrightarrow special RBAC role for e.g. interlock settings)
 - **ADJUST**
 - Perform actions/change minor beam parameters (“minor” needs to be defined)
 - tune beam parameters (within limits) to suit the experiments needs/performance
 - **STABLE BEAMS** – alternate: PRODUCTION (for physics)
 - main intend is to deliver stable beam to experiments
 - tbd: very limited machine tuning
 - **BEAM-DUMP or POST-MORTEM**
 - response to quench, MP action, or other action that needs to be analysed before one can continue with normal operation
 - **RECOVERY**
 - recovering from severe post-mortem, essentially includes 'CYCLING'
- For storage rings (essentially only ESR & HESR)
 - Do we need INJECTION/ACCUMULATION & RAMP modes?

Beam Modes are not new!
already practise in normal operation
→ plan to make CS also aware of them
→ allows to define rules, statistics, ...