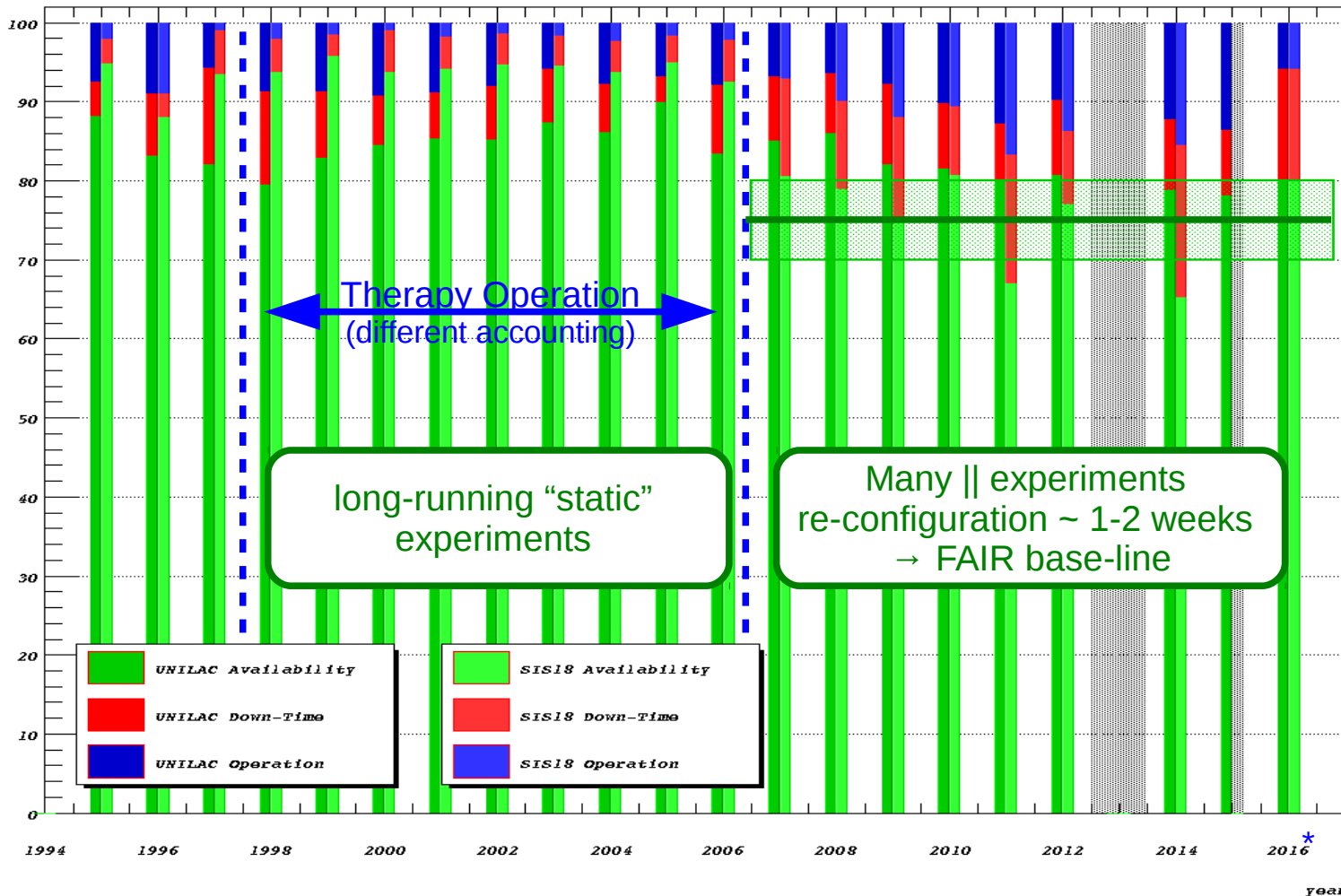


Main MD topic covered:

FAIR Accelerator Controls & Beam-Based Feedbacks Proof-of-Concepts

- Cycle-to-Cycle Orbit Feedback → [details by B. Schlei](#)
- K-modulation Studies - determining SIS18's magnetic centre
- Cycle-to-Cycle macro-spill-structure Feedback (slow-extraction)
 - or: "*The importance of bunnies for FAIR*"

special thanks to: D. Ondreka, P. Spiller, J. Stadlmann, S. Reimann, D. Severin, OP/BI crew on shift ...

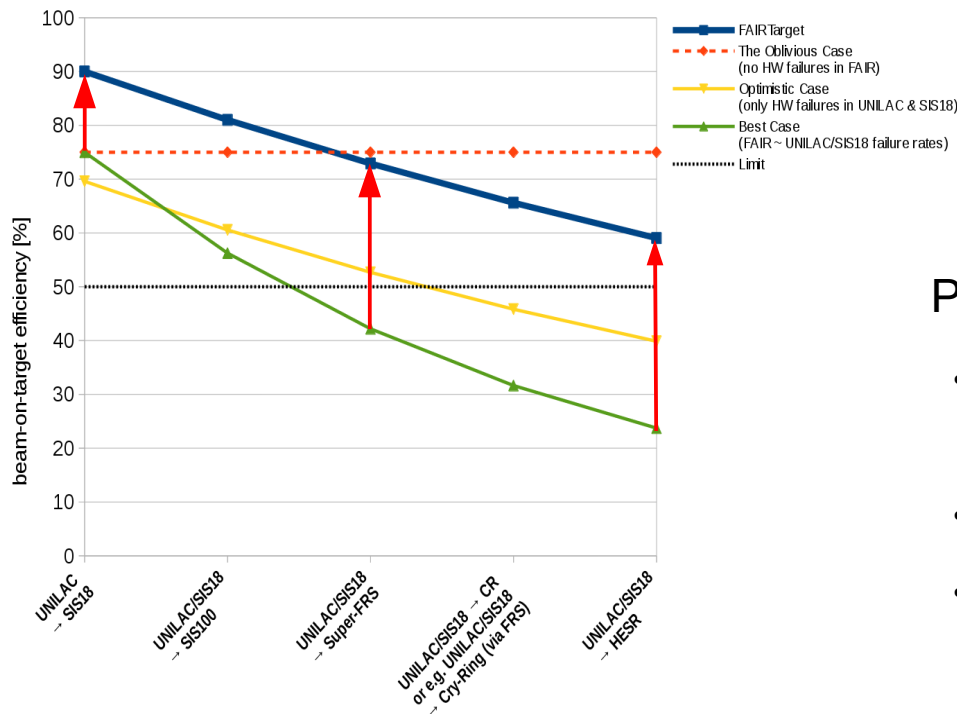


Based on: U. Scheeler, S. Reimann, P. Schütt et al., "Accelerator Operation Report", GSI Annual Scientific Reports 1992 – 2015 + 2016 (D. Severin)
https://www.gsi.de/en/work/research/library_documentation/gsi_scientific_reports.htm
 N.B. ion source exchanges are factored out from UNILAC & SIS18 data (~ constant overhead)
 Availability: experiments + detector tests + machine development + beam to down-stream accelerators;
 Down-time: unscheduled down-time + standby; Operation: accelerator setup + re-tuning

* 2018 operation limitations:
 • only ½ UNILAC (w/o A3 & A4)
 • only 1 element in SIS18

- Beam-on-Target Figure of Merit ~75%
→ FAIR-BoT (efficiency ϵ_{FAIR}):

$$\epsilon_{\text{FAIR}} := \prod_i^{n_{\text{machines}}} \epsilon_i = \epsilon_{\text{UNILAC}} \cdot \epsilon_{\text{SIS18}} \cdot \epsilon_{\text{SIS100}} \cdot \epsilon_{\text{SuperFRS}} \cdot \epsilon_{\text{CR}} \cdot \epsilon_{\text{HESR}} \dots$$



- New Accelerator Operation challenges:
 - ~ 4 x larger facility complexity
 - operation beyond present accelerator & beam parameter envelope:
 - x10 higher beam energies
 - x10-100 higher intensities
- losses/activation & machine protection become important issues

Primary goals:

- maintain existing flexibility/parallelisms
 - N.B. > 3 exp. in || & 1-2 weeks/exp
- better & safe beam control
- efficient operation, target: 15% → <2 %

... across the whole accelerator facility

Generic Beam Control (focus on use-case)

1. [Transmission Monitoring System](#)
(R. Steinhagen, FC²WG Meeting #6)
2. [Orbit Control](#) (work in progress)
3. [Trajectory Control](#) (threading, inj./extr., targets)
4. [Q/Q'\('\) Diagnostics & Control](#)
5. [TL&Ring Optics Measurement + Control](#) (LOCO, AC-dipole techniques etc.,)
6. RF Capture and (later) RF gymnastics
7. Longitudinal Emittance Measurement
8. Transverse emittance measurement
9. Transverse and longitudinal feedbacks

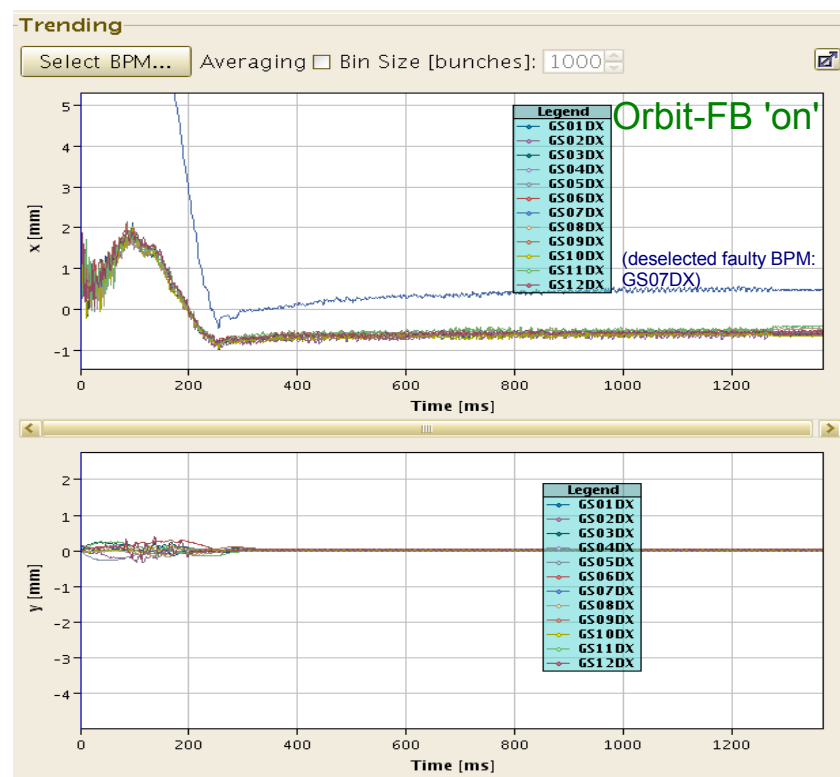
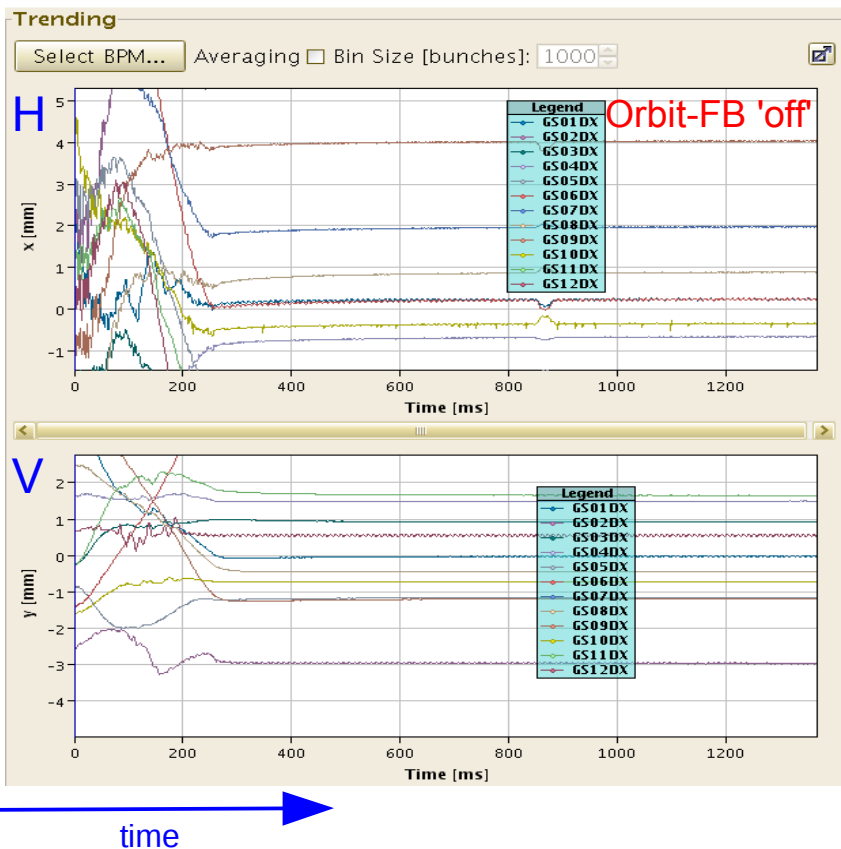
Bread-and-Butter systems for OP ideally for SIS18 restart

Machine-specific Beam-Based Systems:

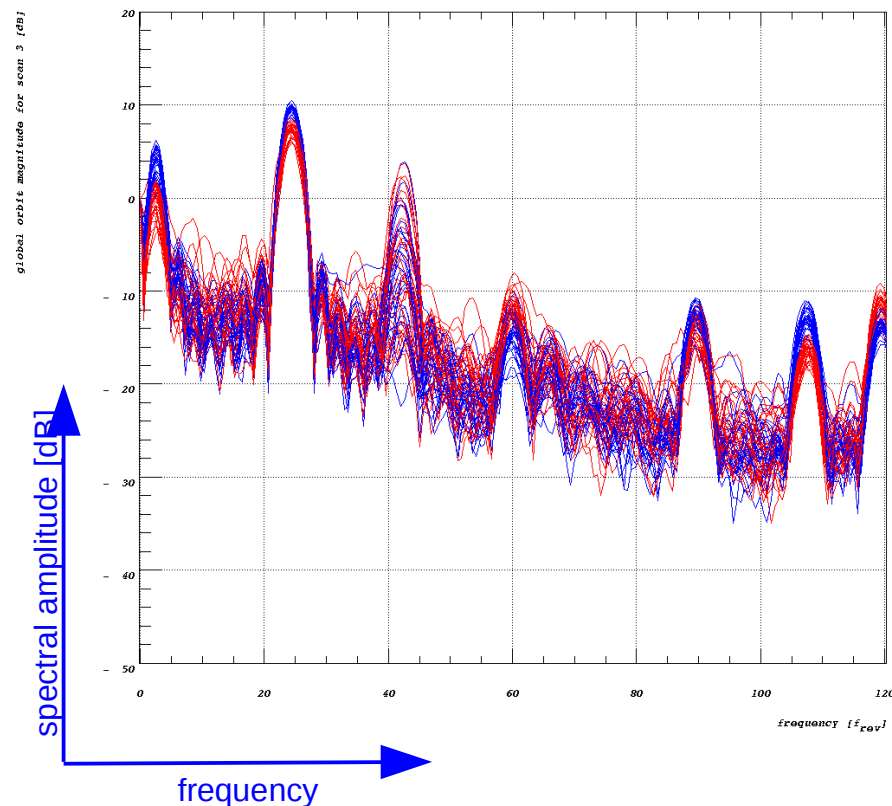
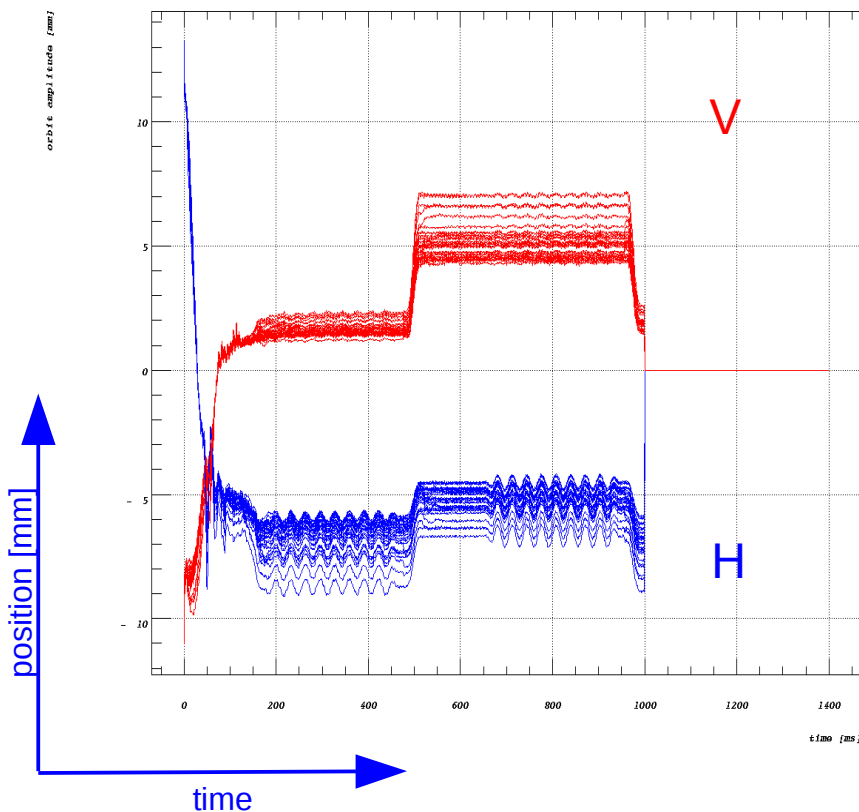
- SIS18: multi-turn-Injection (N.B. highly non-trivial, complex subject), Slow-Extraction (K.O. exciter, spill-structure, ...)
- SIS100: Slow-Extraction (K.O. exciter, spill-structure ...), RF Bunch Merging and Compression
- ESR, HESR & CR: Stochastic cooling, Schottky diagnostics, ..., tbd.

Generic:

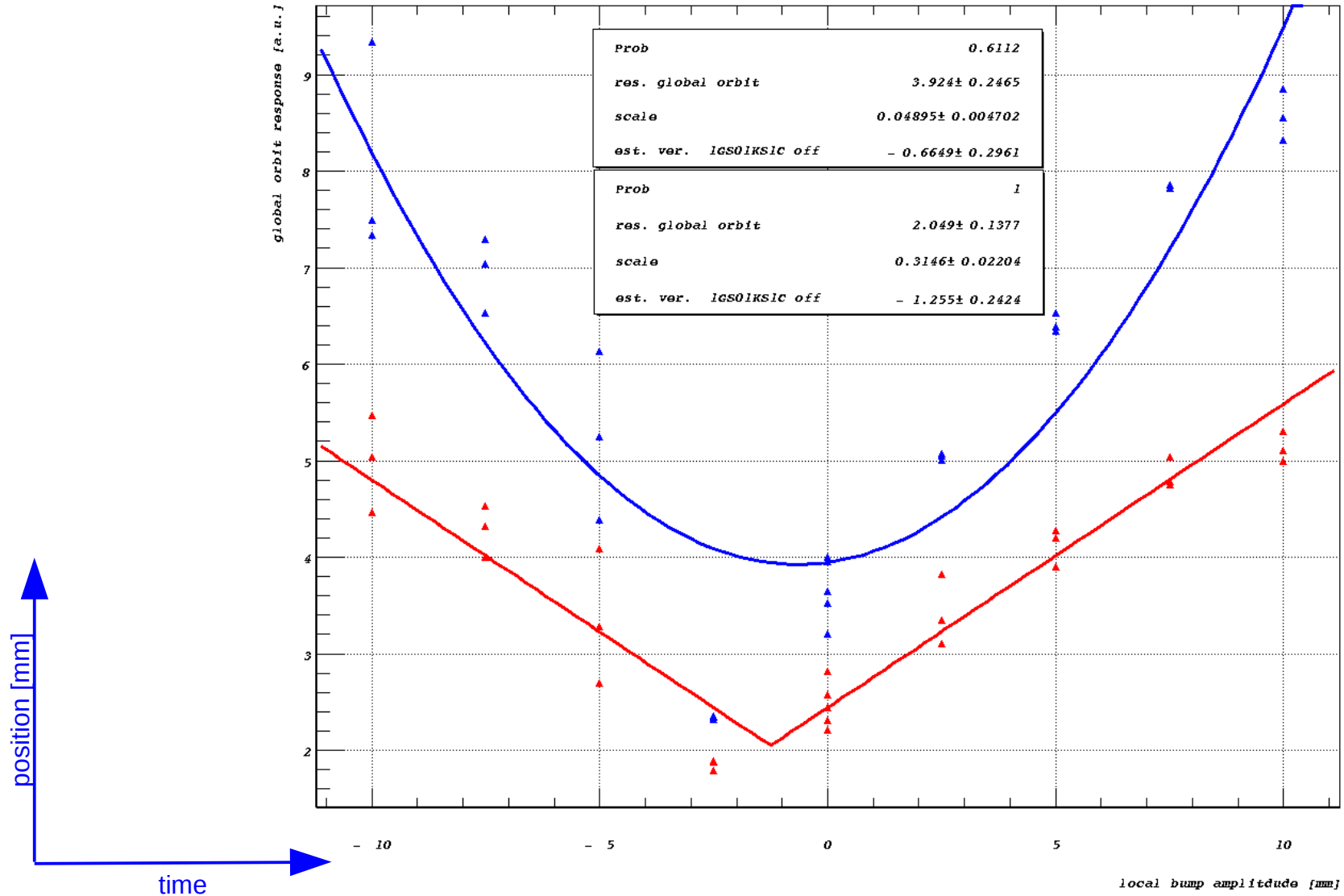
- [Remote DAQ of Analog Signals](#)
(strong impact on HKR migration/operation!)
- Facility-wide fixed-displays, facility & Machine Status (“Page One”)
- context-based monitoring of controls and accelerator Infrastructure,
- ...

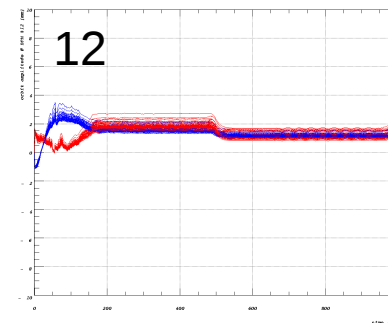
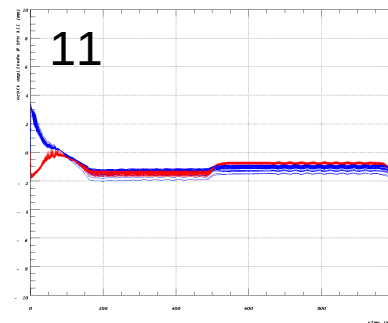
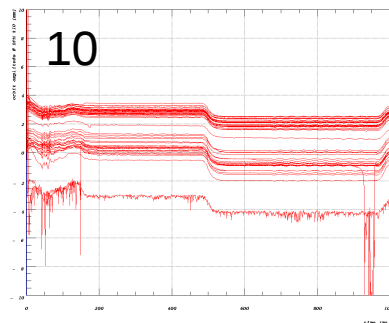
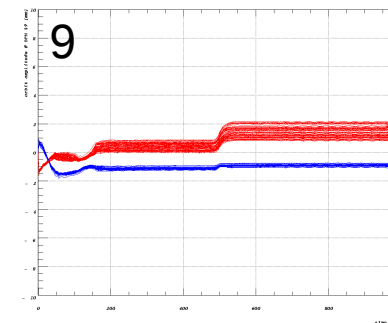
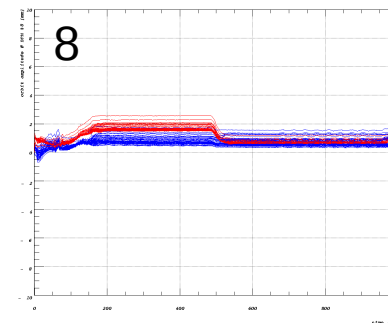
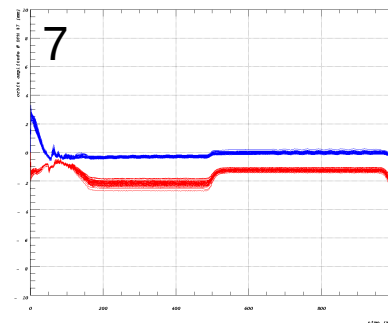
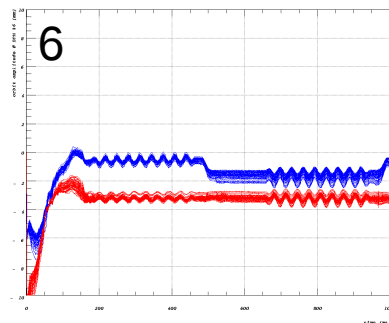
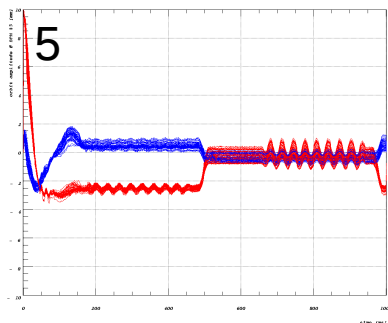
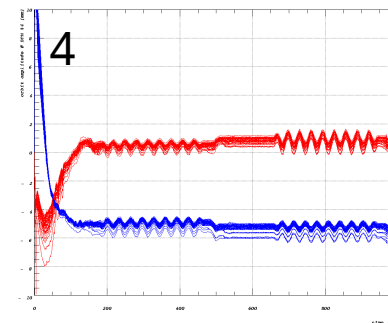
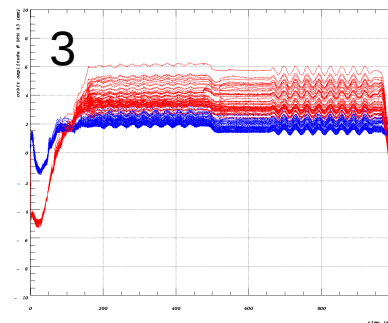
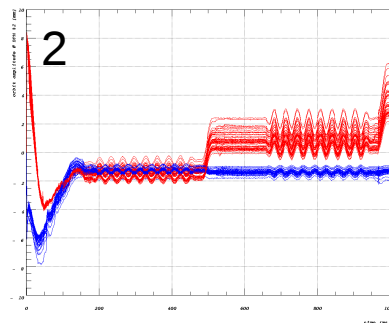
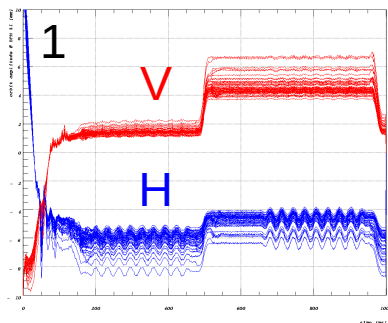


- some workarounds needed, but overall success and results look promising
 - need to follow-up: reliability, performance issues related to CO & BI + detailed integration before being put into regular operation (→ routine operation for >2018 looks feasible)
 - N.B. remaining horizontal oscillation due to uncorrected $\Delta p/p$ mismatch → radial-loop/Energy-FB

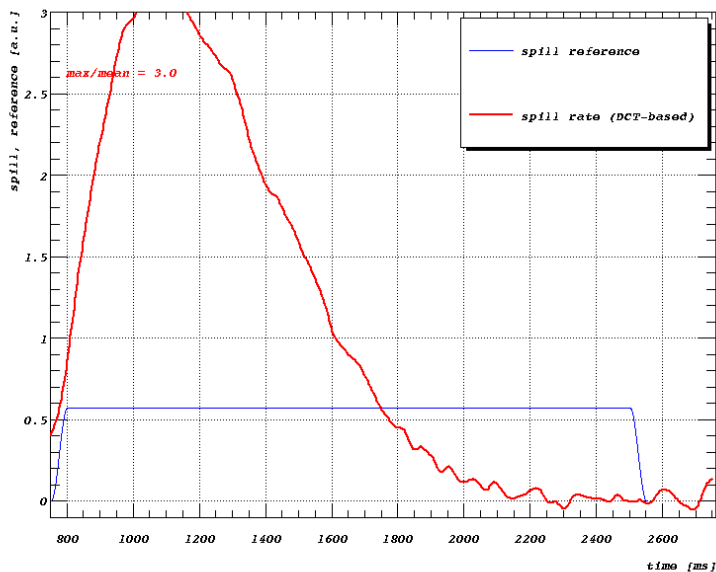


- ~ 700 nearly fully autonomous measurements (night-shift activity)
- some workarounds needed, but overall success and results look promising
 - need to follow-up: BI reliability, performance issues

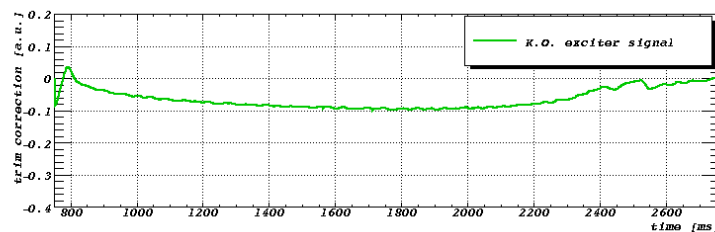
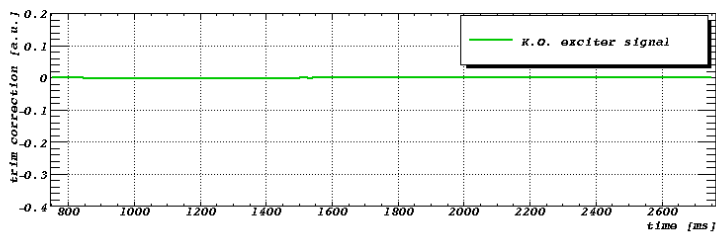
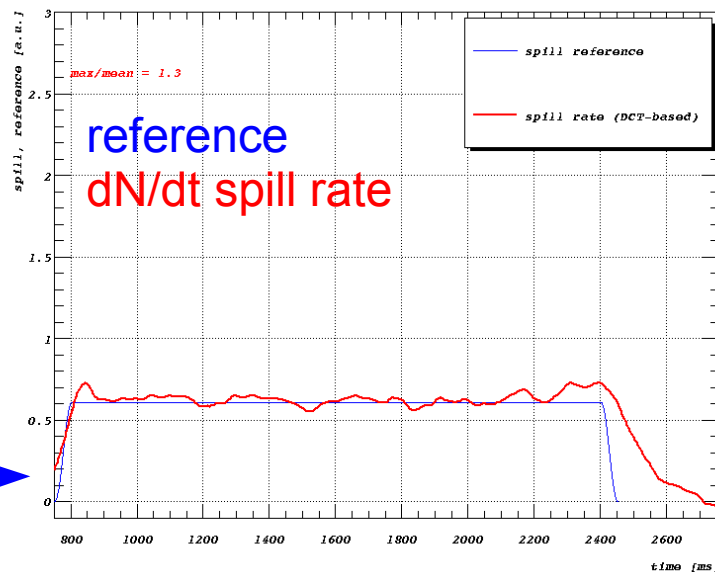




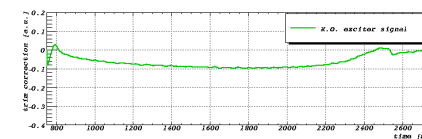
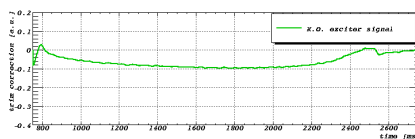
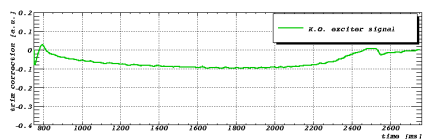
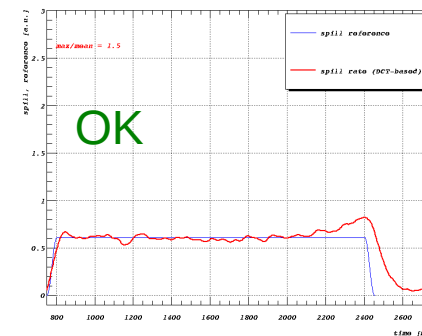
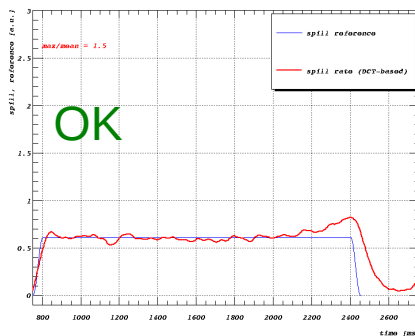
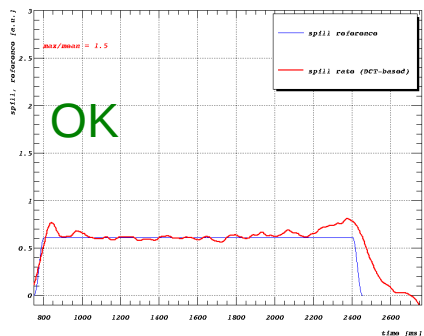
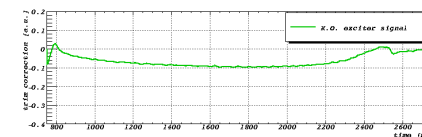
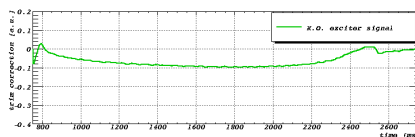
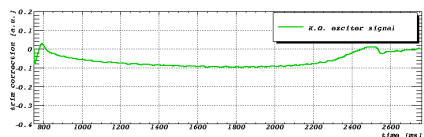
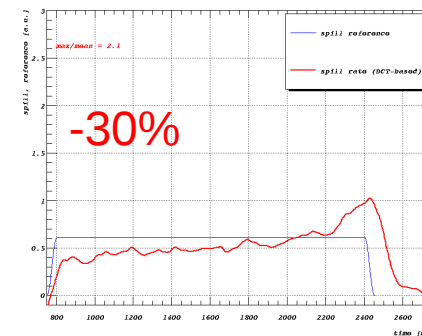
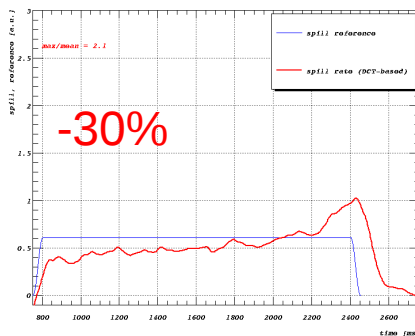
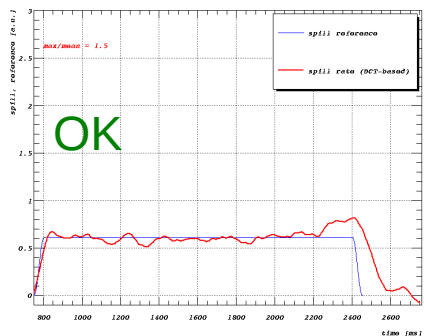
↑ orbit -10 .. +10 mm
 → time: 0 → 1 s

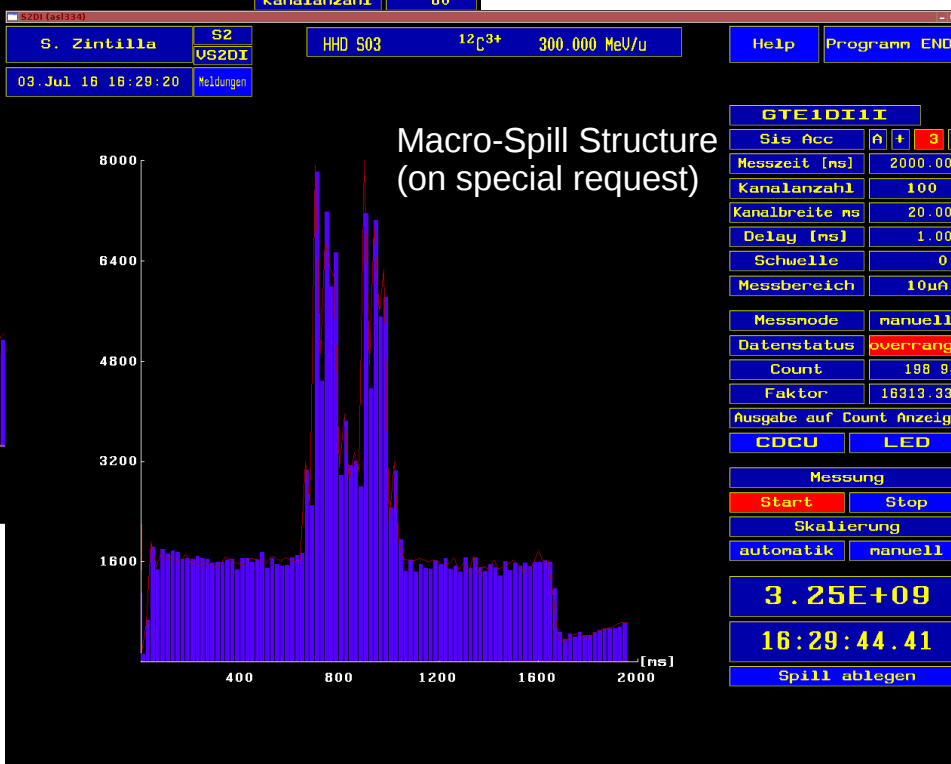
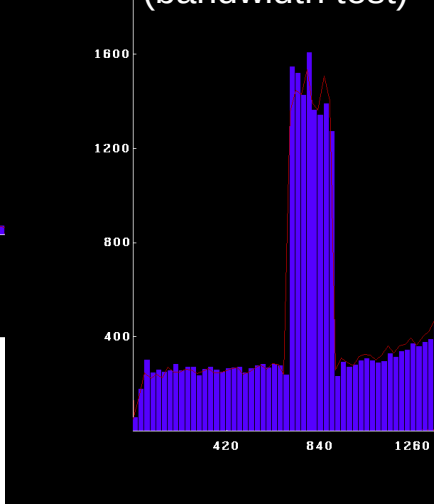
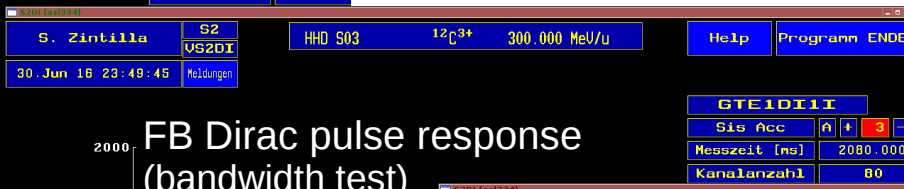
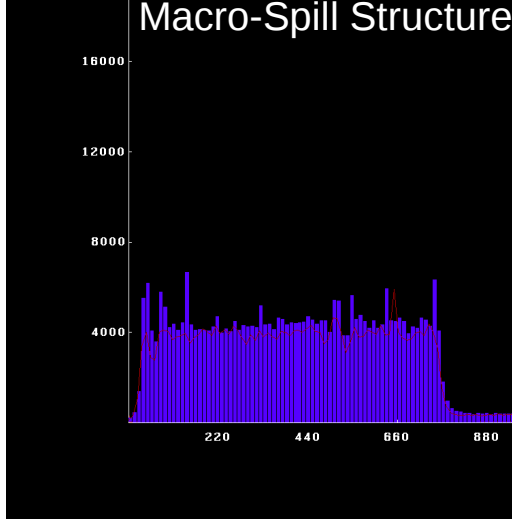
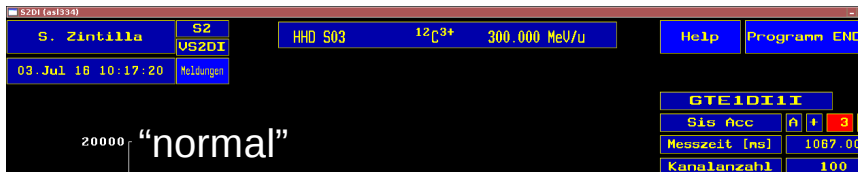


Fill-to-Fill
 FB on dN/dt
 (DCCT-based)

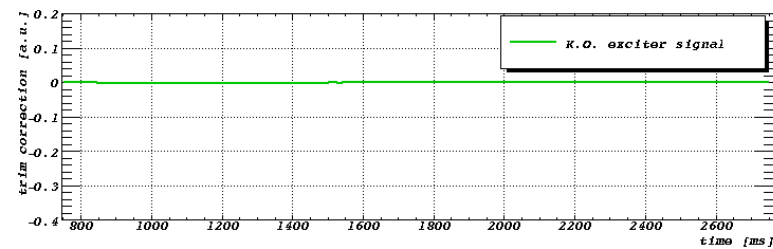
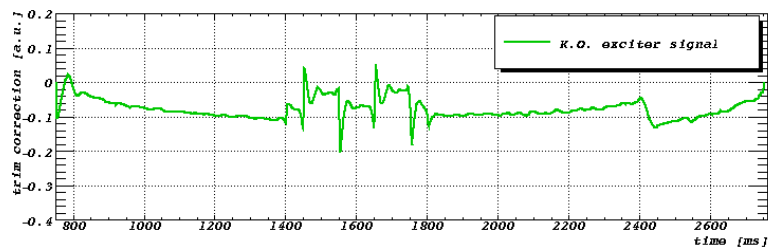
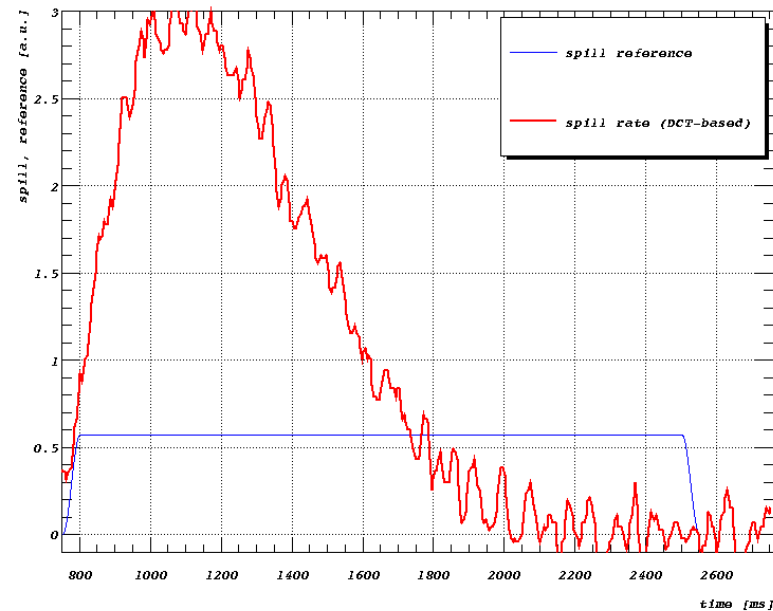
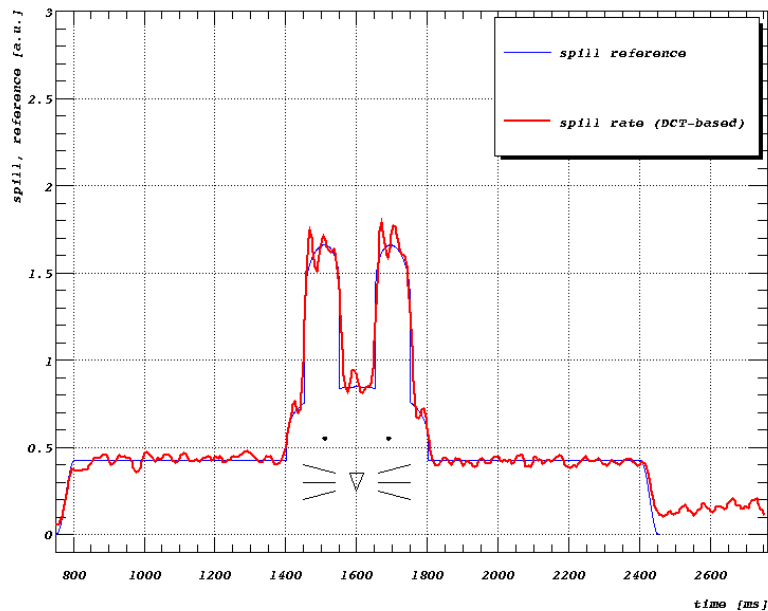


- some workarounds needed, but overall success and results look promising
 - need to follow-up: K.O. exciter power-limitation handling (easily for >10 Tm operation)
 - Alternative: FB using fast extraction quadrupole or main-quads
 - Desirable: direct FB signal from experimental detectors
 - routine operation for 2018 feasible (provided priority/manpower will be allocated for OP/CO integration)





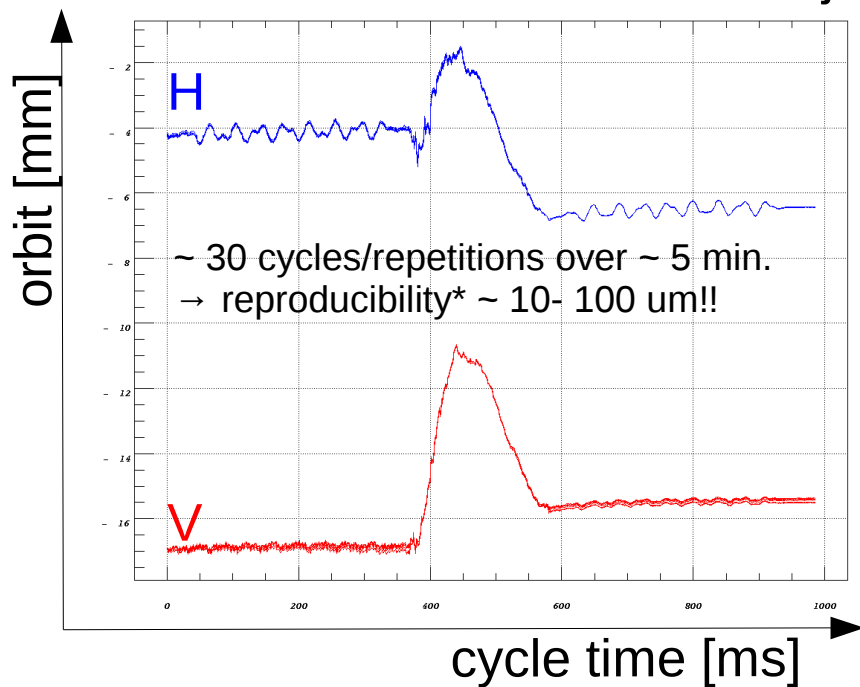
animated GIF - link





Yes, we can!

1. Orbit/Trajectory (e.g.Target-) Steering

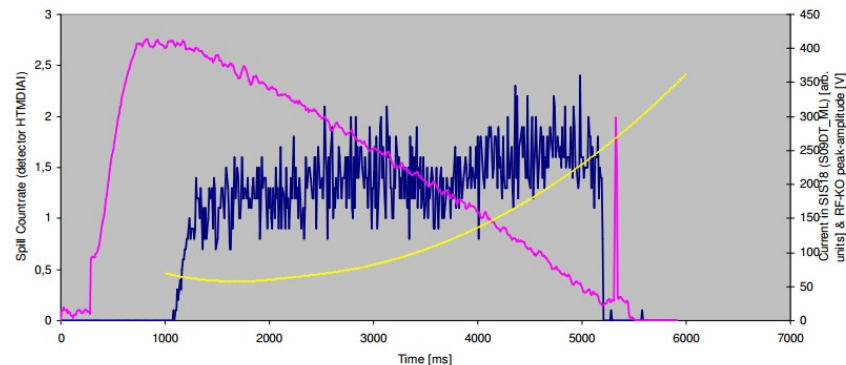


2. Macro-Spill Feedback

Measurement
Beam: $^{12}\text{C}^{6+}$
Energy: ~300 MeV/u

SIS-18:
29 July 2011

— HTMDIAI
— S09DT_ML
— KO amplitude

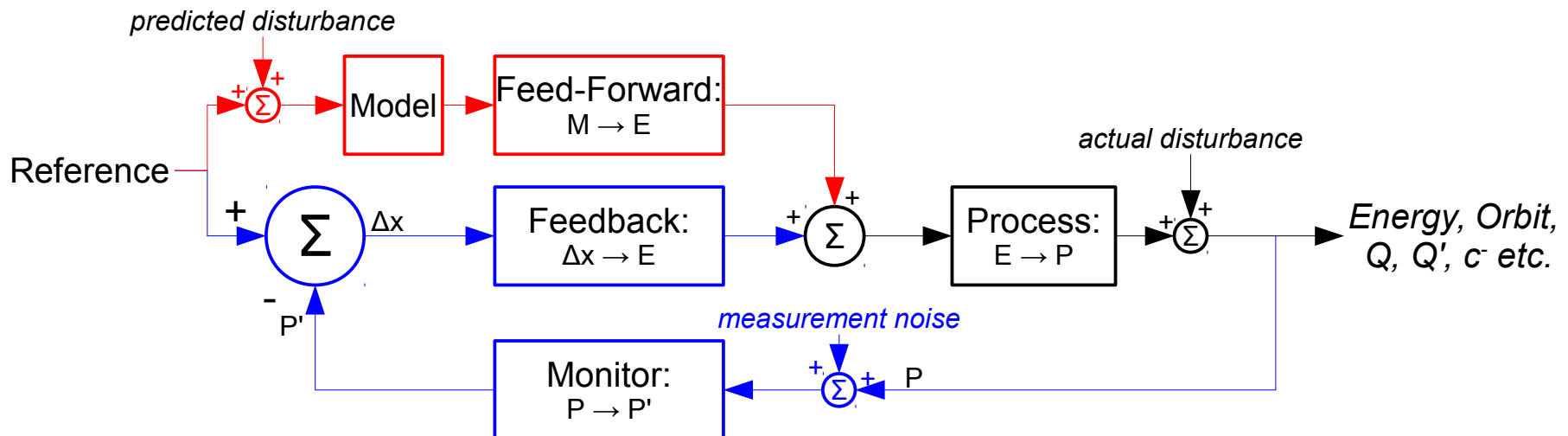


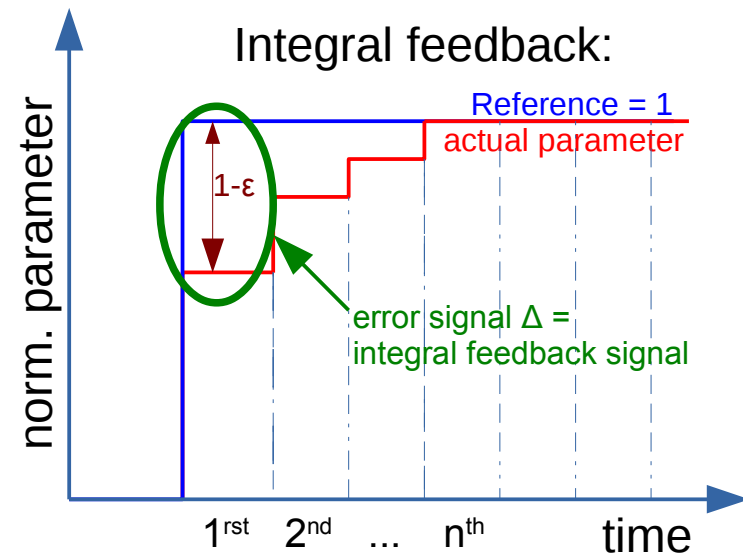
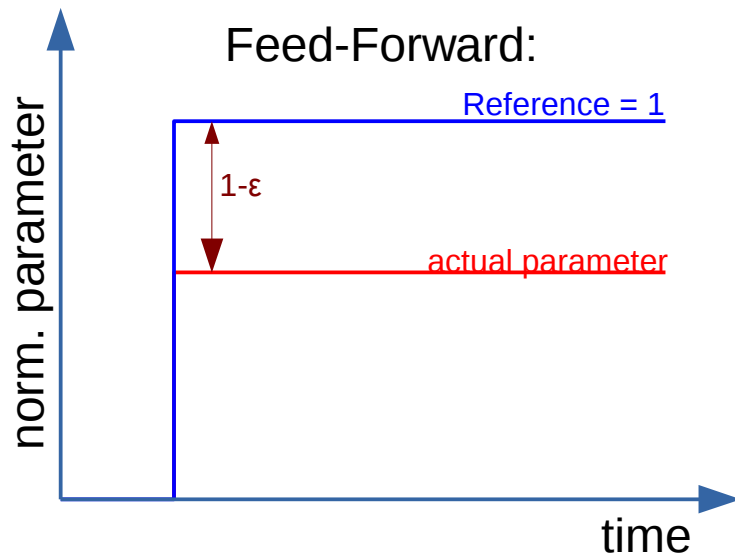
courtesy C. Bert, A. Constantinescu, D. Ondreka, M. Kirk et. al.

*modulo BPM stability/bias

- **Feed-Forward: (FF)**
 - Steer parameter using precise process model and disturbance prediction

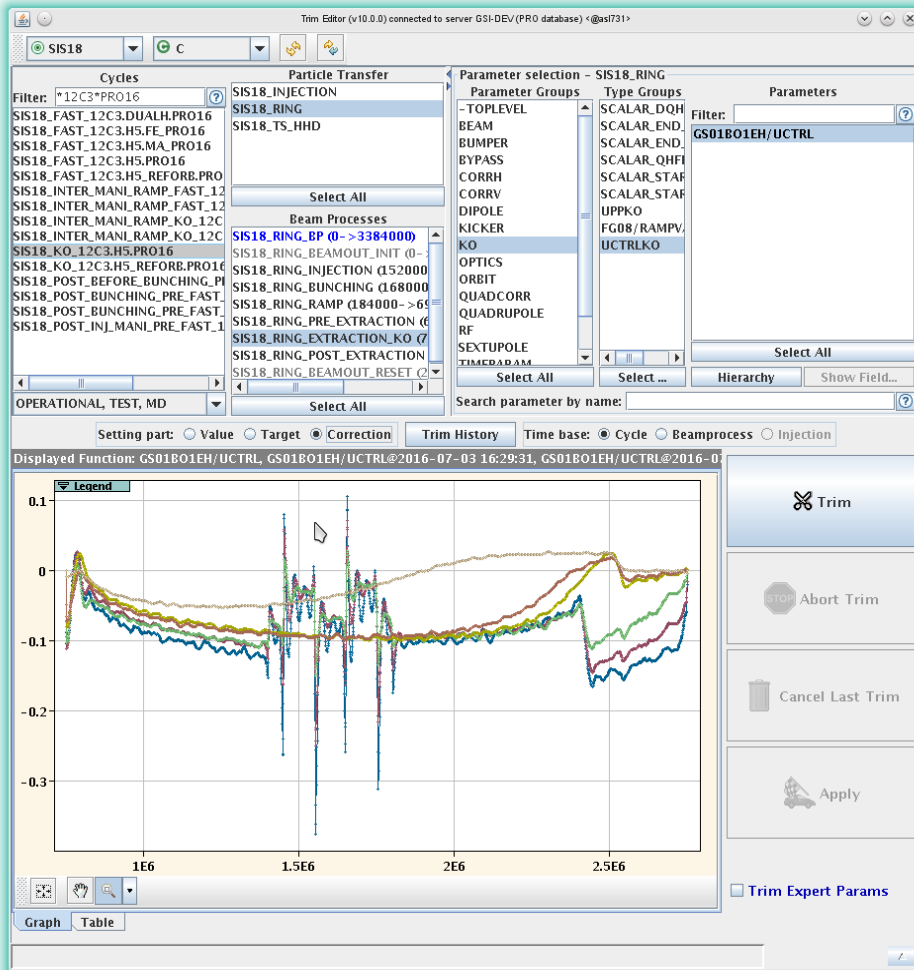
- **Feedback: (FB)**
 - Steering using rough process model and measurement of parameter
 - Two types: within-cycle (repetition $\Delta t \ll 10$ hours) or cycle-to-cycle ($\Delta t > 10$ hours)





Uncertainties and scale error of beam response function affects convergence speed (= feedback bandwidth) rather than achievable stability

Generic LSA trim interface:

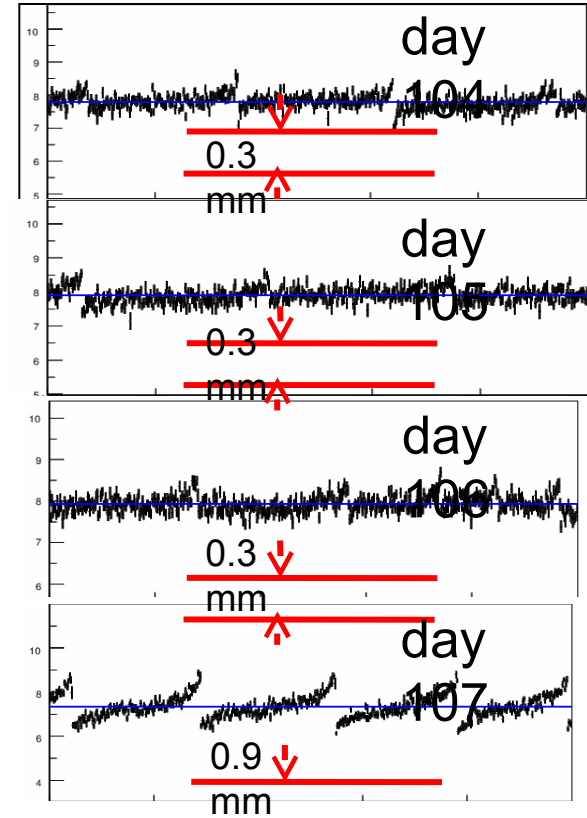
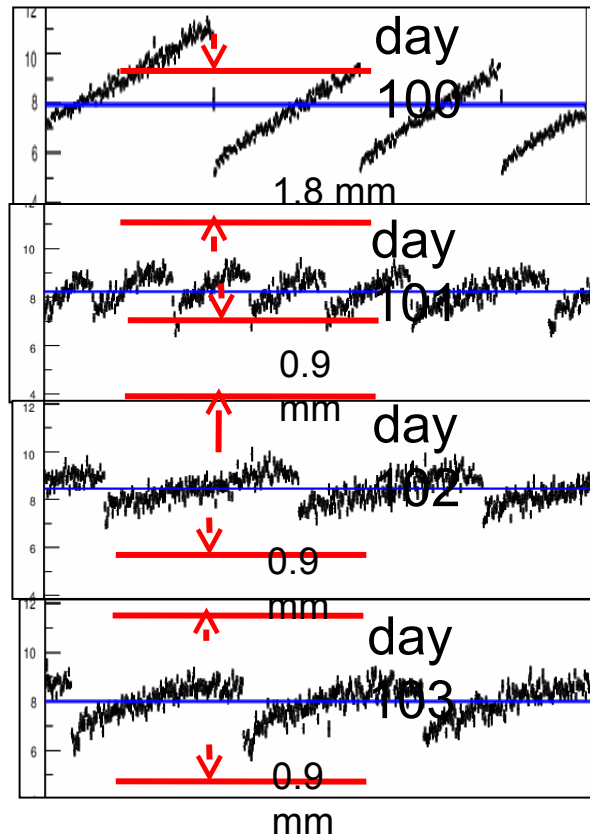
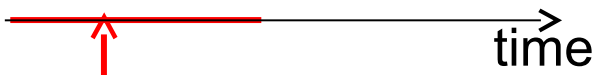
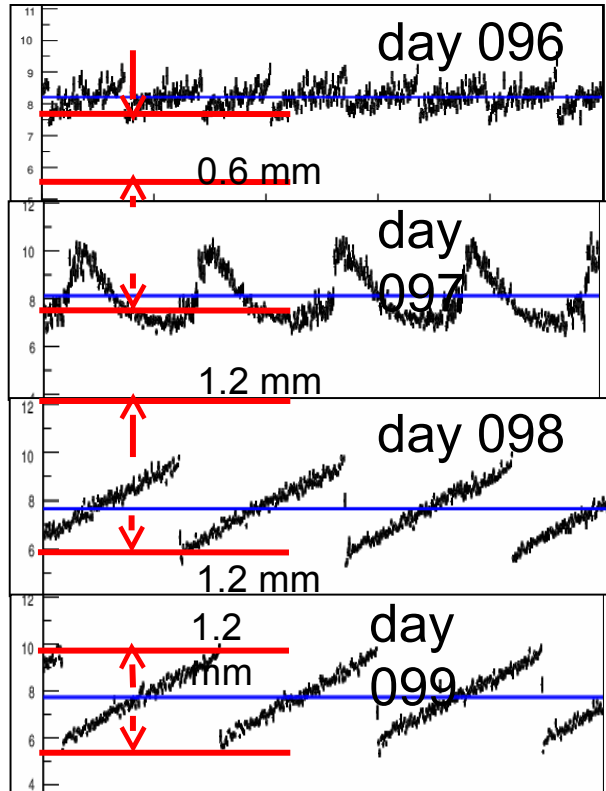


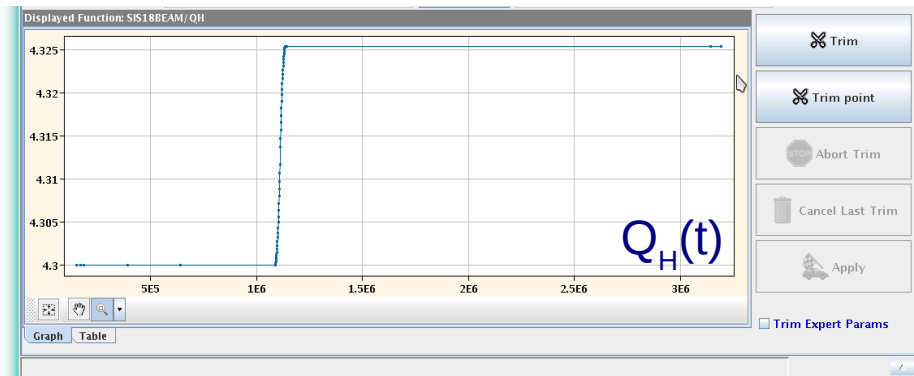
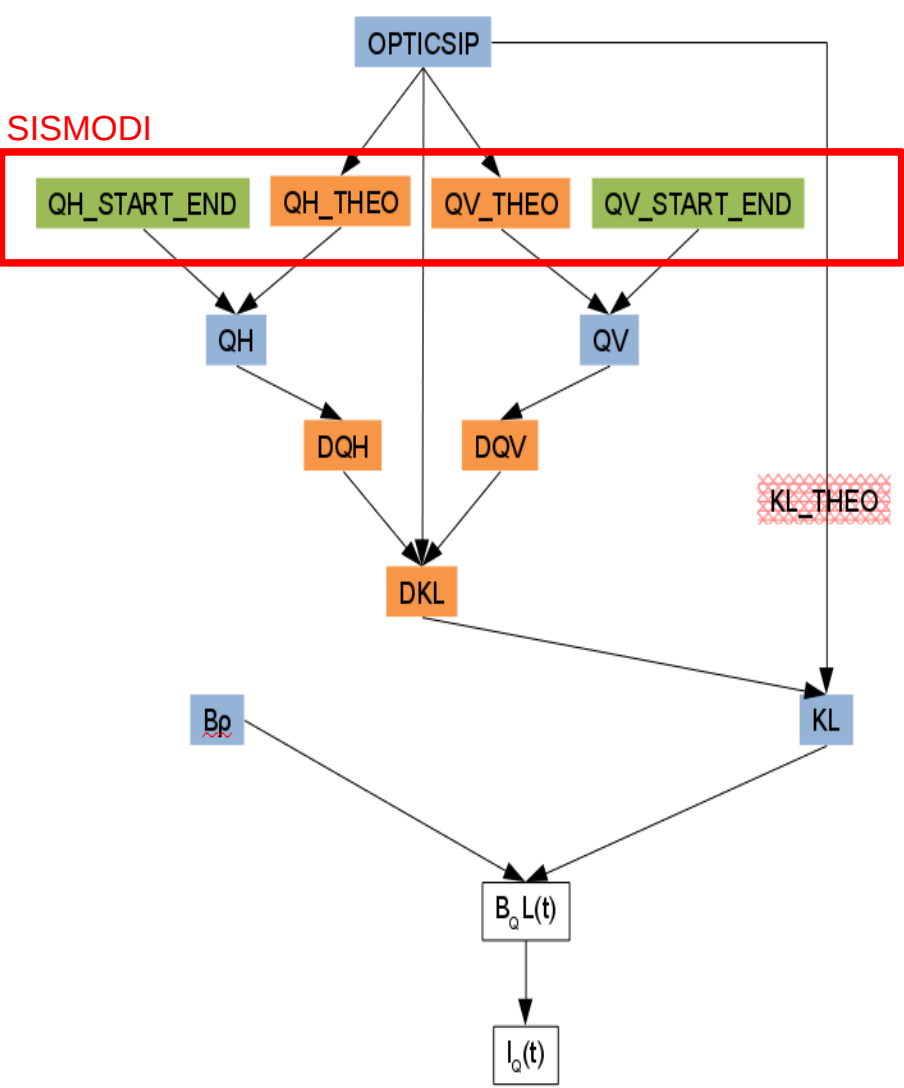
... open to all accelerator parameter that fulfil basic control theory criteria:

- **Stability:** “parameter should be ~ reproducible from fill-to-fill ... “
 - good OP experience provided hysteresis is respected
- **Controllability:** “need affine (but not necessarily linear dependence between observable effect and control actuator, ...”
- **Observability:** “... need to be able to measure it reliability (noise, ...), ...”
 - *N.B. interface to experiment's detectors*



Beam position stability – day-wise





- Integrated Luminosity per experiment

$$\frac{\int \mathcal{L}(t) dt}{\left[\int \mathcal{L} dt \right]_{\text{ref}}} \sim \int_{\text{OP year}} \underbrace{\frac{dN_{\text{ions}}/dt}{\epsilon_{x,y,s}}}_{\text{Experiment constraints}} \cdot \underbrace{\epsilon_{\text{FAIR}}}_{\text{FAIR efficiency (simplified)}} dt$$

Experiment constraints:

- dN_{ions}/dt constant (spill-structure)
- $dN_{\text{ions}}/dt|_{\text{max}}$ constraints
- ...
- **beam brightness:** N_{ions} & $\epsilon_{x,y,s}$
 - x 10-100 higher intensities N_{ions}
 - x 10 beam energies
 - **new:**
 - machine protection
 - activation/loss minimisation (ALARA)

FAIR efficiency (simplified):

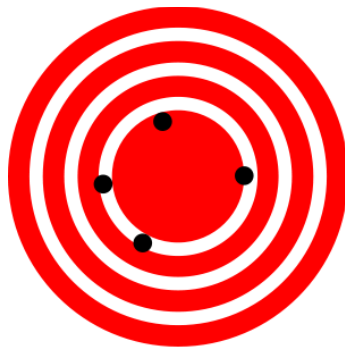
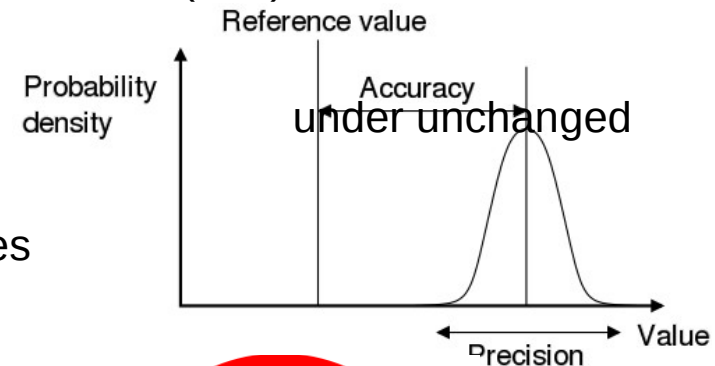
$$\epsilon_{\text{FAIR}} \approx \frac{\langle t_{\text{physics}} \rangle}{\langle t_{\text{physics}} \rangle + \langle t_{\text{operation}} \rangle + \langle t_{\text{down-time}} \rangle}$$

Primary FC²WG goals:

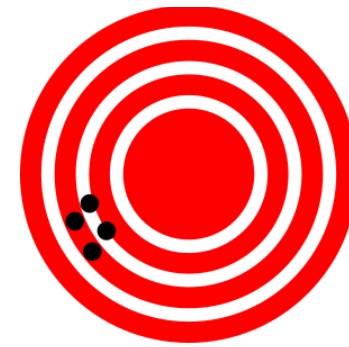
1. efficient operation
 2. better & safe beam control
- ... across the whole accelerator facility

Good summary: http://en.wikipedia.org/wiki/Accuracy_and_precision

- **Accuracy:** “[..] closeness of measurements [..] to its actual (true) value”
- **Precision** (also: reproducibility or repeatability): “[..] degree to which repeated measurements conditions show the same results.”
- Example: “Target analogy” and the two extreme cases



High **accuracy**, but low **precision**
obtained through beam-based alignment



High **precision**, but low **accuracy**
we need this from the BPMs

- **Resolution:** smallest change that produces a response in the measurement